

IN THE SUBSTITUTE SPECIFICATION:

Please replace paragraph [0032] starting at page 10, line 15 of the substitute specification with the following replacement paragraph:

[0032] A stator 50, which is rotationally fixed against the rotor and the last member of the robot arm 3, has a tubular leadthrough 14 arranged in the middle (centrally) in the welding torch device, which has a cylindrical recess 15. A longitudinal axis 16 of the recess 15 is aligned with the rotational axis 8 of the connection flange 6. The leadthrough 14 extends approximately over the entire length of the fixing device and of the receiving device. The upper end of the leadthrough 14 on the robot side is provided with an outer threaded section 17 serving as an electrical connection, to which a coaxial cable 18 (Figure 1 and Figure 2) can be detachably fixed by means of screwing on. In addition to the threaded section 17 of the leadthrough, a cone 19 (Figure 3) may also be provided as a current-conducting contact between a welding power cable 18a of the coaxial cable 18 and the leadthrough 14. In such a coaxial cable 18, the welding power cable 18a, provided with an outer insulation 18b, is arranged coaxially about a central channel 18c. The central channel 18c may be used to supply a welding wire 20 to the welding torch by means of a feed motion and to let an inert gas flow to the welding torch.